

Where Automation Connects.



inRAx[®] MVI56E-MCMR

ControlLogix Platform

Enhanced Modbus Master/Slave Communications Module with Reduced Data Block

June 29, 2010



Important Safety Information - MVI56E Modules

North America Warnings

- A Warning Explosion Hazard Substitution of components may impair suitability for Class I, Division 2.
- **B** Warning Explosion Hazard When in Hazardous Locations, turn off power before replacing or rewiring modules.

Warning - Explosion Hazard - Do not disconnect equipment unless power has been switched off or the area is known to be nonhazardous.

C Suitable for use in Class I, Division 2 Groups A, B, C, and D, T5 Hazardous Locations or Non-Hazardous Locations.

ATEX Warnings and Conditions of Safe Usage

Power, Input, and Output (I/O) wiring must be in accordance with the authority having jurisdiction

- A Warning Explosion Hazard When in hazardous locations, turn off power before replacing or wiring modules.
- **B** Warning Explosion Hazard Do not disconnect equipment unless power has been switched off or the area is known to be non-hazardous.
- **C** These products are intended to be mounted in an IP54 enclosure. The devices shall provide external means to prevent the rated voltage being exceeded by transient disturbances of more than 40%. This device must be used only with ATEX certified backplanes.
- D DO NOT OPEN WHEN ENERGIZED.

Electrical Ratings

- Backplane Current Load: 800 mA @ 5 Vdc; 3 mA @ 24 Vdc
- Operating Temperature: 0°C to 60°C (32°F to 140°F)
- Storage Temperature: -40°C to 85°C (-40°F to 185°F)
- Shock: 30 g operational; 50 g non-operational; Vibration: 5 g from 10 to 150 Hz
- Relative Humidity 5% to 95% (without condensation)
- All phase conductor sizes must be at least 1.3 mm (squared) and all earth ground conductors must be at least 4mm (squared).

Markings

ANSI / ISA	ISA 12.12.01 Clas	s I Division 2, GPs /	А, В, С, D
CSA/cUL	C22.2 No. 213-M1	987	
CSA CB Certified	d IEC61010		
ATEX	EN60079-0 Categ	ory 3, Zone 2	
	EN60079-15		
(Ex)		c UL us	RoHS
2	243333	E183151	
CL I Div 2 GP A,	B, C, D		

Temp Code T5

II 3 G

Ex nA nL IIC T5 X

0°C <= Ta <= 60°C

- II Equipment intended for above ground use (not for use in mines).
- 3 Category 3 equipment, investigated for normal operation only.

G – Equipment protected against explosive gasses.

Battery Life Advisory

The module uses a rechargeable Lithium Vanadium Pentoxide battery to backup the real-time clock and CMOS settings. The battery itself should last for the life of the module. However, if left in an unpowered state for 14 to 21 days, the battery may become fully discharged and require recharging by being placed in a powered-up ControlLogix chassis. The time required to fully recharge the battery may be as long as 24 hours.

Once it is fully charged, the battery provides backup power for the CMOS setup and the real-time clock for approximately 21 days. Before you remove a module from its power source, ensure that the battery within the module is fully charged (the BATT LED on the front of the module goes OFF when the battery is fully charged). If the battery is allowed to become fully discharged, the module will revert to the default BIOS and clock settings.

Note: The battery is not user-replaceable or serviceable.

ProSoft Technology[®] Product Documentation

In an effort to conserve paper, ProSoft Technology no longer includes printed manuals with our product shipments. User Manuals, Datasheets, Sample Ladder Files, and Configuration Files are provided on the enclosed CD-ROM, and are available at no charge from our web site: www.prosoft-technology.com

Printed documentation is available for purchase. Contact ProSoft Technology for pricing and availability.

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Your Feedback Please

We always want you to feel that you made the right decision to use our products. If you have suggestions, comments, compliments or complaints about our products, documentation, or support, please write or call us.

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MVI56E-MCMR Setup Guide 6/23/2010

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1 Scope

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This document acts as a tutorial in providing step-by-step instructions on how to read and write bi-directional data from one network device to another network device using the MVI56E-MCMR module.

1.1 What's New?

MVI56E products are backward compatible with existing MVI56 ladder logic and module configuration files. You can easily swap and replace products while benefiting from an array of new features designed to improve interoperability and enhance the user experience.

- WEB Page: Use a standard web browser to access the module's web page through the new Ethernet port
- ProSoft Discovery Service (PDS): Allows ProSoft Configuration software and/or separate optional software to find and display a list of all MVI56E modules on the network, and to temporarily change IP addresses to connect with the module web page
- ProSoft Configuration Builder (PCB): New Windows-style graphical user interface (GUI) for configuration and diagnostics with improved graphical screen navigation. Connect via Ethernet port or CIPconnect[®] to upload/download module configuration information
- CIPconnect[®]-enabled: Allows PC-to-module configuration and diagnostics via 1756-ENBT local and remote chassis from anywhere on the Ethernet network using PCB
- Personality Card: A compact flash memory card storing the module's settings, for quick and easy replacement of modules in the field
- LED Scrolling Diagnostic Display: 4-character, alpha-numeric display, providing English messages for status and alarm data, and for processor and network communication conditions

1.2 Learning Objectives

When you have completed all the steps in this Setup Guide, you will have learned how to

- Use the sample application (page 17)
- Install the MVI56E-MCMR setup and diagnostic software (page 15)
- Install the MVI56E-MCMR module (page 23)
- Import the Add-On Instruction to the processor (page 47)
- Configure the Modbus Master (page 51) using the sample Add-On Instruction
- Configure the Modbus Slave (page 56)
- Verify the MVI56E-MCMR module communication status (page 58)

1.3 **ProSoft Technology Documentation**

ProSoft Technology provides the following documentation (manuals) with your MVI56E-MCMR.

Electronic documentation (on the MVI56E-MCMR web page)

- Setup Guide: (this manual) Describes the sample application, and takes you through the steps necessary to install, configure, and verify the correct operation of the module
- User Manual: Detailed reference guide to the module, protocol configuration, functional overview, diagnostics and troubleshooting procedures, and product specifications
- Datasheet: Brief description of the module hardware and protocol implementation, general and functional specifications

Additional documentation, tools, and product support

- Email Technical Support: Send your support questions to Support@prosofttechnology.com
- Web Site Support: Visit the ProSoft Technology web site at www.prosoft-technology.com to download additional documentation, tools and application information
- Telephone Support: Please call ProSoft Technology Technical Support at: (Country Code 1+) 661-716-5100. Support is available 24 hours a day, 7 days a week. ProSoft Technology telephone support is free and unlimited

1.4 Prerequisites

To get the most benefit from this *Setup Guide*, you should have the following skills:

- Rockwell Automation[®] RSLogix[™] 5000 software: launch the program, configure, and transfer the Add-On Instruction (or ladder logic) Sample Application program to the processor
- Microsoft Windows[®]: install and launch programs, execute menu commands, navigate dialog boxes and enter data.
- Serial data communication: correctly configure data communication parameters such as baud rate, parity, data bits, and so on, using the documentation for the devices connected to the network
- Ethernet networking: connect the MVI56E-MCMR module to an Ethernet network using a valid IP address and subnet mask
- Hardware installation and wiring: install the module and safely connect Modbus Master/Slave and ControlLogix devices to a power source and to the MVI56E-MCMR module's serial ports

2 Before You Begin

In This Chapter

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2.1 System Requirements

The MVI56E-MCMR module requires the following minimum hardware and software components:

- Rockwell Automation ControlLogix[®] processor (firmware version 10 or higher), with compatible power supply, and one free slot for the MVI56E-MCMR module. The module requires 800 mA of available 5 Vdc power
- Rockwell Automation RSLogix 5000 programming software
 - Version 16 or higher required for Add-On Instruction
 - Version 15 or lower must use Sample Ladder, available from www.prosoft-technology.com
- Rockwell Automation RSLinx[®] communication software version 2.51 or higher
- ProSoft Configuration Builder (PCB) (included)
- ProSoft Discovery Service (PDS) (included in PCB)
- Pentium[®] II 450 MHz minimum. Pentium III 733 MHz (or better) recommended
- Supported operating systems:
 - Microsoft Windows[®] Vista
 - Microsoft Windows XP Professional with Service Pack 1 or 2
 - Microsoft Windows 2000 Professional with Service Pack 1, 2, or 3
 - Microsoft Windows Server 2003
- 128 Mbytes of RAM minimum, 256 Mbytes of RAM recommended
- 100 Mbytes of free hard disk space (or more based on application requirements)
- 256-color VGA graphics adapter, 800 x 600 minimum resolution (True Color 1024 × 768 recommended)
- CD-ROM drive

Note: The Hardware and Operating System requirements in this list are the minimum recommended to install and run software provided by ProSoft Technology[®]. Other third party applications may have different minimum requirements. Refer to the documentation for any third party applications for system requirements.

Note: You can install the module in a local or remote rack. For remote rack installation, the module requires EtherNet/IP or ControlNet communication with the processor.

2.2 Required Items

This Setup Guide uses a sample application that shows you how to establish communication between the MVI56E-MCMR module (Master Port) and a Modbus Slave device. The sample application requires the following equipment.

Item	Description
MVI56E-MCMR	Enhanced Modbus Master/Slave Communications Module with Reduced Data Block
1756-L63	ControlLogix processor
1756-A7/B	2 ControlLogix racks: one local rack with processor and one remote rack with MVI56E-MCMR
1756-PA72/B	2 ControlLogix rack power supplies: one local rack and one remote rack
1756-ENBT/A	2 EtherNet/IP Bridge Modules, one local rack and one remote rack
CPU434 12A	Quantum processor (Modbus device)
CPS 114 20	Quantum power supply
140XBP01000	Quantum rack
Ethernet cable	Ethernet cable to connect MVI56E-MCMR module to Ethernet network for diagnostics (supplied with the module)
Serial cable	Serial cable to connect MVI56E-MCMR module to Modbus serial network

Note: Other remote communication configurations are also possible. Please refer to your Rockwell Automation documentation for information on communicating with a remote rack.

2.3 Sample Files

The following file is required for this procedure:

Item	Description	
MVI56(E)MCMR_AddOn_Rung_v1_2.L5X	Sample rung import file containing Add-On Instruction	

This procedure requires RSLogix 5000 version 16 (or later), which supports Add-On Instructions. The sample MVI56(E)MCMR_AddOn_Rung_v1_2.L5X Add-On Instruction file contains all elements required for the MVI56E-MCMR module to function.

- User-defined Data Types (UDTs)
- Add-On Instruction (AOI)
- Ladder rung with AOI
- Controller tags

The AOI L5X rung import file is located on the module's built-in web page.

Note: For RSLogix v15 (or older) applications, please refer to the *MVI56E-MCMR User Manual* for information on how to use the sample ladder logic.

3 Install the Configuration Tools

In This Chapter

3.1 Install ProSoft Discovery Service

You must install the ProSoft Discovery Service (PDS) software in order to configure the MVI56E-MCMR module's temporary IP address. This will allow you to access the module's web page to download product documentation and sample files and to set the module's permanent network address and settings.

To install ProSoft Discovery Service from the CD-ROM

1 Insert the ProSoft Solutions CD-ROM into the CD drive of your PC. Wait for the startup screen to appear.



- 2 On the startup screen, click **INSTALL PROSOFT DISCOVERY SERVICE**. This action starts the installation wizard.
- **3** Click **NEXT** on each page of the installation wizard. Click **FINISH** on the last page of the wizard.

4 The Sample Application

In This Chapter

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4.1 About the MODBUS Protocol

MODBUS is a widely-used protocol originally developed by Modicon in 1978. Since that time, the protocol has been adopted as a standard throughout the automation industry.

The original MODBUS specification uses a serial connection to communicate commands and data between Master and Slave devices on a network. Later enhancements to the protocol allow communication over other types of networks.

MODBUS is a Master/Slave protocol. The Master establishes a connection to the remote Slave. When the connection is established, the Master sends the MODBUS commands to the Slave. The MVI56E-MCMR module can work as a Master and as a Slave.

The MVI56E-MCMR module also works as an input/output module between itself and the Rockwell Automation backplane and processor. The module uses an internal database to pass data and commands between the processor and Master and Slave devices on MODBUS networks.

4.2 General Overview

This Setup Guide shows you how to configure the MVI56E-MCMR module and establish communication with a Modbus device (a Quantum processor, for this example).

The MVI56E-MCMR Port 1 (P1) will be configured as a Modbus Master device. The Quantum processor will operate as a Modbus Slave device (Modbus Comm 1). The MVI56E-MCMR will be configured to send two Master commands to the Modbus Slave device:

- Write 10 words (Modbus Function 16 Preset [Write] Multiple Registers
- Read 10 words (Modbus Function 3 -Read Holding Registers



When you finish the steps in this Setup Guide, you will have enough information to set up your own application.

4.2.1 Required Steps

This Setup Guide will take you through the following steps:

- 1 Install the ProSoft Module in the rack (page 23)
- 2 Use the Add-On Instruction to Configure the Module (page 37)
- **3** Connect your PC to the Processor (page 46)
- 4 Download the Sample Program to the Processor (page 47)
- 5 Set up the Read and Write Database Areas
 - **a** Configure Modbus Port 1 (P1)
 - **b** Configure the Modbus Master Read Command (page 52, page 53)
 - c Configure the Modbus Master Write Command
- 6 Reboot the module
- 7 Set up the Quantum Processor Modbus Slave Port (page 56)
- **8** Verify Communication (page 58)

4.3 Architecture

The sample application uses the following hardware and connections.

- A Personal Computer running a supported version of Microsoft Windows, with a web browser, RSLogix 5000, ProSoft Discovery Service and an Ethernet port
- A ControlLogix processor with MVI56E-MCMR module acting as a Modbus Master
- A Quantum processor acting as a Modbus Slave
- An Ethernet network connecting the PC with the MVI56E-MCMR, either directly or through an Ethernet hub or switch.
- An RS-232 serial cable connecting the MVI56E-MCMR Modbus Master Port 1 to the Quantum processor Modbus Slave Port.

The following illustration shows the sample application.



4.4 Memory Map

The memory map consists of the starting addresses for Read Data and Write Data areas in the MVI56E-MCMR module and in the Quantum processor. The sample application reads and writes 10 words between the Modbus Master and the Modbus Slave.

The following table describes the memory map for data transfer between the MVI56E-MCMR module and the Quantum processor.

Function	MVI56E-MCMR Database Start Address (Master)	Quantum Memory Start Address (Slave)	Word Count
Read	1000	400801	10
Write	0	400401	10

5 Procedures

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*	Connect the MVI56E-MCMR Module to the Quantum Processor
*	Verify Communication

5.1 Physical Setup

5.1.1 Set Module Jumpers

There are three jumpers located at the bottom of the module. The first two jumpers (PRT1 and PRT2) set the serial communication mode: RS-232, RS-422, or RS-485.

The following illustration shows the MVI56E-MCMR jumper configuration.



- 1 The sample application will connect the MVI56E-MCMR application port P1 to the target device using the supplied null-modem cable (RS-232). Set the PRT1 jumper for RS-232.
- 2 The Setup Jumper acts as "write protection" for the module's flash memory. In "write protected" mode, the Setup pins are not connected, and the module's firmware cannot be overwritten. The module is shipped with the Setup pins jumpered, so that you can update the module's firmware if necessary. As you will not be updating the firmware for this procedure, remove the setup jumper and store it in a safe place (for example, on only one of the pins).

Note: If you are installing the module in a remote rack, you may prefer to leave the Setup pins jumpered. That way, you can update the module's firmware without requiring physical access to the module.

5.1.2 Install the Module in the Remote Rack

If you have not already installed and configured your ControlLogix processor, remote rack, and 1756-ENBT EtherNet/IP Bridge modules connecting the processor to the remote rack, please do so before installing the MVI56E-MCMR module. Refer to your Rockwell Automation product documentation for installation instructions.

Important: The Sample Application describes a MVI56E-MCMR module operating in a remote ControlLogix rack. The sample application will also work with the MVI56E-MCMR module in the same rack with the processor.

Warning: You must follow all safety instructions when installing this or any other electronic devices. Failure to follow safety procedures could result in damage to hardware or data, or even serious injury or death to personnel. Refer to the documentation for each device you plan to connect to verify that suitable safety procedures are in place before installing or servicing the device.

After you have checked the placement of the jumpers, insert MVI56E-MCMR into the ControlLogix chassis. Use the same technique recommended by Rockwell Automation to remove and install ControlLogix modules.

You can install or remove ControlLogix system components while chassis power is applied and the system is operating. However, please note the following warning.

Warning: When you insert or remove the module while backplane power is on, an electrical arc can occur. An electrical arc can cause personal injury or property damage by:

- sending an erroneous signal to your system's actuators causing unintended machine motion or loss of process control
- causing an explosion in a hazardous environment

Verify that power is removed or the area is non-hazardous before proceeding. Repeated electrical arcing causes excessive wear to contacts on both the module and its mating connector. Worn contacts may create electrical resistance that can affect module operation.

1 Align the module with the top and bottom guides, and then slide it into the rack until the module is firmly against the backplane connector.



- 2 With a firm but steady push, snap the module into place.
- 3 Check that the holding clips on the top and bottom of the module are securely in the locking holes of the rack.
- 4 Make a note of the slot location. You must identify the slot in which the module is installed in order for the sample program to work correctly. Slot numbers are identified on the green circuit board (backplane) of the ControlLogix rack.
- 5 Turn power ON.

Note: If you insert the module improperly, the system may stop working, or may behave unpredictably.

5.1.3 Connect Your PC to the Module's Ethernet Port

With the module securely mounted, connect one end of the Ethernet cable to the **ConFig (E1)** Port, and the other end to an Ethernet hub or switch accessible from the same network as your PC. Or, you can connect directly from the Ethernet Port on your PC to the **ConFig (E1)** Port on the module.



5.1.4 Set Temporary IP Address

Important: ProSoft Configuration Builder locates MVI56E-MCMR modules through UDP broadcast messages. These messages may be blocked by routers or layer 3 switches. In that case, ProSoft Discovery Service will be unable to locate the modules.

To use ProSoft Configuration Builder, arrange the Ethernet connection so that there is no router/ layer 3 switch between the computer and the module OR reconfigure the router/layer 3 switch to allow the routing of the UDP broadcast messages.

1 Click the **START** button, and then navigate to **PROGRAMS / PROSOFT TECHNOLOGY**

Microsoft Update Set Program Access and Defaults		
Windows Catalog Windows Update	Accessories Administrative Tools)
Programs	ProSoft Technology	ProSoft Configuration Builder
 Documents Settings Search 	 Internet Explorer Paint Windows Media Player 	 ProSoft Transport Path Editor ProSoft Discovery Service
 Help and Support Run 		
Shut Down start		

2 Click to start **PROSOFT CONFIGURATION BUILDER**

If you have used other Windows configuration tools before, you will find the screen layout familiar. PCB's window consists of a tree view on the left, and an information pane and a configuration pane on the right side of the window. When you first start *PCB*, the tree view consists of folders for **DEFAULT PROJECT** and **DEFAULT LOCATION**, with a **DEFAULT MODULE** in the Default Location folder. The following illustration shows the *PCB* window with a new project.

ile <u>V</u> iew <u>P</u> roject <u>T</u> ools <u>H</u> elp					
🖃 🧰 Default Project		Name	Status	Information	
🗄 🔚 Default Location	4	New Module Unknown Product Line	Please Select Module Type		
		Last Change: Last Download:	Never Never		
	# # # #	<pre># Module Information # Last Change: Never # Last Download: Never # Application Rev: # OS Rev: # Loader Rev: # MAC Address:</pre>	r		
	#	≠ ConfigEdit Version: ≠ Module Configuratio Modulel	n		
	Ň	iodule Type : Iodule Name : New Mod	lule New Module		

3 Use the mouse to select **DEFAULT MODULE** in the tree view, and then click the right mouse button to open a shortcut menu.

4 On the shortcut menu, choose **CHOOSE MODULE TYPE**. This action opens the **CHOOSE MODULE TYPE** dialog box.

Choose Mo	dule Type					X
		Produc	t Line Filter—			
C All				○ MVI56 ④ MVI56E		
		Search	Module Type -			
STEP 1: 3	Select Module T	уре	Module Defini	tion:		_
MVI56E- MVI56E- MVI56E- MVI56E- MVI56E- MVI56E-	MCM MCMR MNET MNETC MNETCR		Acti	on Required		J
				ОК	Cancel	

- 5 In the PRODUCT LINE FILTER area of the dialog box, select MVI56E. In the SELECT MODULE TYPE dropdown list, select MVI56E-MCMR, and then click OK to save your settings and return to the ProSoft Configuration Builder window.
- 6 Right click over the module icon.



7 On the shortcut menu, choose **DIAGNOSTICS.**



This action opens the **DIAGNOSTICS** dialog box.



If there is no response from the module,



1 Click the **SET UP CONNECTION** button to browse for the module's IP address.



2 On the **CONNECTION SETUP** dialog box, click the **TEST CONNECTION** button to verify if the module is accessible with the current settings

Connection Setup				
Select Connection Type: Ethernet				
Ethernet				
ProSoft Discovery Service (PDS) Browse Device(s)				
CIPconnect				
t:192.168.0.100,p:1,s:0				
CIP Path Edit				
Test Connection Connect Cancel				

3 If PCB is still unable to connect to the module, click the **BROWSE DEVICE(S)** button to open the **PROSOFT DISCOVERY SERVICE**. 4 Select the module, then right click and choose **Assign TEMPORARY IP**.



5 The module's default IP address is 192.168.0.250.

🖪 Assign Temporary IP Address 🛛 🗖 🔯					
Temporary IP::	192 . 168 . 0 . 250				
Network Mask:	255 . 255 . 255 . 0				
ОК	Cancel				

6 Choose an unused IP within your subnet, and then click OK.

<u>CIPconnect</u>

You can use CIPconnect[®] to connect a PC to the MVI56E-MCMR module over Ethernet using Rockwell Automation's 1756-ENBT EtherNet/IP[®] module. This allows you to configure the MVI56E-MCMR module and network, upload and download files, and view network and module diagnostics from a PC. RSLinx is not required when you use CIPconnect. All you need are:

- The IP addresses and slot numbers of any 1756-ENBT modules in the path
- The ControlNet node numbers and slot numbers of any 1756-CNBx ControlNet Bridge modules in the path
- The slot number of the MVI56E-MCMR in the destination ControlLogix chassis (the last ENBT/CNBx and chassis in the path).

To use CIPconnect, follow these steps.

1 In the **SET CONNECTION TYPE** dropdown list, choose 1756-ENBT. The default path appears in the text box, as shown in the following illustration.

c	onnection Setup
	Select Connection Type: 1756-ENBT
	Ethemet
	ProSoft Discovery Service (PDS) Browse Device(s)
	CIPconnect
	t:192.168.0.100,p:1,s:0
	CIP Path Edit
	Test Connection Connect Cancel

2 Click **CIP PATH EDIT** to open the **CIPCONNECT PATH EDITOR** dialog box.

C	CIPconnect Path Editor						
		PConr	nect™ PA⁻	ГН ЕDIT	OR		
	No	Source Module	Source Module IP Address	Source Module Node Address	Destination Module		Destination Module Slot Number
	1	1756-ENBT	192.168.0.100		MVI56-Module	~	0
	. 100						
	1:192	168.0.100,p:1,s:0	Add Rack OK		Construct CIP Path		

The **CIPCONNECT PATH EDITOR** allows you to define the path between the PC and the MVI56E-MCMR module. The first connection from the PC is always a 1756-ENBT (Ethernet/IP) module.

Each row corresponds to a physical rack in the CIP path.

- If the MVI56E-MCMR module is located in the same rack as the first 1756-ENBT module, select **RACK No. 1** and configure the associated parameters.
- If the MVI56E-MCMR is available in a remote rack (accessible through ControlNet or Ethernet/IP), include all racks (by using the ADD RACK button).

Parameter	Description		
Source Module	Source module type. This field is automatically selected depending on the destination module of the last rack (1756-CNB or 1756-ENBT).		
Source Module IP Address	IP address of the source module (only applicable for 1756-ENBT)		
Source Module Node Address	Node address of the source module (only applicable for 1756-CNB)		
Destination Module	Select the destination module associated to the source module in the rack. The connection between the source and destination modules is performed through the backplane.		
Destination Module Slot Number	The slot number where the destination MVI56E module is located.		

To use the CIPconnect Path Editor, follow these steps.

- 1 Configure the path between the 1756-ENBT connected to your PC and the MVI56E-MCMR module.
 - If the module is located in a remote rack, add more racks to configure the full path.
 - The path can only contain ControlNet or Ethernet/IP networks.
 - The maximum number of supported racks is six.
- 2 Click **CONSTRUCT CIP PATH** to build the path in text format
- 3 Click **OK** to confirm the configured path.

5.1.5 Connect to the Module's Web Page

- 1 In ProSoft Discovery Service, select the module to configure, and then click the right mouse button to open a shortcut menu.
- 2 On the shortcut menu, choose VIEW MODULE'S WEBPAGE.



The web page contains the product documentation and sample programs.



Important: The temporary IP address is only valid until the next time the module is initialized. Please refer to Set Temporary IP Address (page 26) in the MVI56E-MCMR User Manual for information on how to set the module's permanent IP address.

5.1.6 Upload the Add-On Instruction from the Module

Configuration and control information for the MVI56E-MCMR module is provided as an Add-On Instruction for RSLogix 5000, version 16 or higher.



Two Add-On Instructions are provided:

- The Rung IMPORT WITH SAMPLE PROGRAM ADD-ON INSTRUCTION: MVI56(E)MCMR_AddOn_Rung_v1_2.L5X Includes the User Defined Data Types, data objects and ladder logic required to configure the MVI56E-MCMR module.
- The RUNG IMPORT WITH UTILITY ADD-ON INSTRUCTION (OPTIONAL): MVI56(E)MCMR_Optional_Rung_v1_1.L5X Includes the data types and controller tags that allow you to update the IP address, date and time on the module.
Create a new RSLogix 5000 project

1 Open the **FILE** menu, and then choose **NEW**...

8 F	SLogix 5000		
<u>F</u> ile	$\underline{E}dit \underline{V}iew \underline{S}earch \underline{L}ogic \underline{C}ommunications$	<u>T</u> ools	W
Ē	<u>N</u> ew	Ctrl+N	
Ê	<u>O</u> pen	Ctrl+O	
	<u>C</u> lose		
	Save	Ctrl+S	
	Save <u>A</u> s		

- 2 Select your ControlLogix controller model.
- 3 Select **Revision 16**.
- 4 Enter a name for your controller, such as "My_Controller".
- 5 Select your ControlLogix chassis type.6 Select SLOT 0 for the controller.

Vendor:	Allen-Bradley		
<u>T</u> ype:	1756-L63 ControlLogix5563 Controller	•	OK
Re <u>v</u> ision:	16 💌		Cancel
	E <u>R</u> edundancy Enabled		Help
Na <u>m</u> e:	My_Controller		
Descri <u>p</u> tion:		^	
		~	
<u>C</u> hassis Type:	1756-A4 4-Slot ControlLogix Chassis	•	
Sl <u>o</u> t:	0 Safety Partner Slot:	_	
Cr <u>e</u> ate In:	C:\RSLogix 5000\Projects		Browse

Create the Remote Network

1 Right-click I/O CONFIGURATION and choose New MODULE...



2 Expand the **COMMUNICATIONS** module selections and then select the Ethernet Bridge module that matches your hardware. This example uses a 1756-ENBT/A module.

Select Module		X
la co		
Module	Description	Vendor
1756-CNBR/E	1756 ControlNet Bridge, Redundant Media	Allen-Bradley 📩
1756-DHRIO/B	1756 DH+Bridge/RIO Scanner	Allen-Bradley
1756-DHRIO/C	1756 DH+Bridge/RIO Scanner	Allen-Bradley
1756-DHRIO/D	1756 DH+ Bridge/RIO Scanner	Allen-Bradley
1756-DNB	1756 DeviceNet Scanner	Allen-Bradley
1756-EN2F/A	1756 10/100 Mbps Ethernet Bridge, Fiber Media	Allen-Bradley 🔜
1756-EN2T/A	1756 10/100 Mbps Ethernet Bridge, Twisted-Pair Media	Allen-Bradley
	1756 10/100 Mbps Ethernet Bridge, Fiber Media	Allen-Bradley 📃
1756-ENBT/A	1756 10/100 Mbps Ethernet Bridge, Twisted-Pair Media	Allen-Bradley
1756-ENET/A	1756 Ethernet Communication Interface	Allen-Bradley 💻
1756-ENET/B	1756 Ethernet Communication Interface	Allen-Bradley
1756-EWEB/A	1756 10/100 Mbps Ethernet Bridge w/Enhanced Web Serv.	. Allen-Bradley
1756-SYNCH/A	SynchLink Interface	Allen-Bradley 🚩
		•
	Find	Add Favorite
By Category By V	endor Favorites	
	OK Cancel	Help

Note: If you are prompted to "Select Major Revision", choose the lower of the available revision numbers.

3 Name the ENBT/A module, then set the IP Address and slot location in the local rack with the ControlLogix processor.

Name: Local_ENBT1 Address / Host Name	
Name: Local_ENBT1	
Description:	
	120
Sector Host Name:	
Sl <u>o</u> t: 1 🕂	
Revision: 1 - 1 - Electronic Keying: Compatible Keying	-
Revision: 1 🗾 1 🛨 Electronic Keying: Compatible Keying	•

- 4 Click OK.
- 5 Next, select the **1756-ENBT** module that you just created in the Controller Organization pane and click the right mouse button to open a shortcut menu. On the shortcut menu, choose **New MODULE**.

er Ta er Fa Jp Ha ips ped A tructi ratior ackpla 1756	gs ult Handler indler ixes ons	7
¥	Cut	Ctrl+X
	Сору	Ctrl+C
B	Paste	Ctrl+V
	Delete	Del
	Cross Reference	Ctrl+E
	Properties	Alt+Enter

6 Repeat steps 2 and 3 to add the second EtherNet/IP module to the remote rack.

Create the Module - Remote Rack

1 Select the remote **1756 BACKPLANE** node in the Controller Organization pane underneath the remote rack EtherNet/IP module you just created and click the right mouse button to open a shortcut menu. On the shortcut menu, choose **New Module**.



This action opens the **SELECT MODULE** dialog box.

Select Module		X
Module ⊕ Analog ⊕ Communications ⊕ Digital ⊕ Drives ⊕ Motion ⊖ Other □ 1756-MODULE ⊕ Specialty	Description Generic 1756 Module	Vendor Allen-Bradley
By Category By V	endor Favorites OK	Eind Add Favorite

2 Select the **1756-MODULE (GENERIC 1756 MODULE)** from the list and click **OK.** This action opens the **New MODULE** dialog box.

New Module						×
Туре:	1756-MODULE Generic 1756 Module					
Parent:	Local	- Connection Pa	arameters			
			Assembly Instance:	Size:		
Na <u>m</u> e:	MCMR	<u>I</u> nput:	1	42	- (16-bit)	
Description:		O <u>u</u> tput:	2	42	• (16-bit)	
	~	Configuration:	4	0	• (8-bit)	
Comm <u>F</u> ormat	Data - INT	<u>S</u> tatus Input:				
Sl <u>o</u> t:	1 ÷	Status Output		,		
			_			_
Upen Mod	uļe Properties	OK	Can	cel	Help	

Parameter	Value
Name	Enter a module identification string. The recommended value is MCMR, as this name will be linked automatically with the MSG paths, irrespective of the slot location.
Description	Enter a description for the module. Example: ProSoft communication module for Modbus Serial protocol communications.
Comm Format	Select DATA-INT (*Very Important*)
Slot	Enter the slot number in the rack where the MVI56E-MCMR module is to be installed.
Input Assembly Instance	1
Input Size	42
Output Assembly Instance	2
Output Size	42
Configuration Assembly Instance	4
Configuration Size	0

3 Set the Module Properties values as follows:

4 On the **CONNECTION** tab, set the **RPI** value for your project. Fifty (50) milliseconds is usually a good starting value.

Module Properties: Local:2 (1756-MODULE 1.1)
General Connection Module Info Backplane
Requested Packet Interval (RPI): 50.0 + ms (0.2 - 750.0 ms) Inhibit Module Major Fault On Controller If Connection Fails While in Run Mode
Module Fault
Status: Offline OK Cancel Apply Help





Import the Ladder Rung

- 1 In the **CONTROLLER ORGANIZATION** window, expand the **TASKS** folder and subfolder until you reach the **MAINPROGRAM** folder.
- 2 In the MAINPROGRAM folder, double-click to open the MAINROUTINE ladder.
- 3 Select an empty rung in the new routine, and then click the right mouse button to open a shortcut menu. On the shortcut menu, choose **IMPORT RUNG...**



4 Navigate to the location on your PC where you saved (page 36) the Add-On Instruction (for example, "My Documents" or "Desktop"). Select the MVI56(E)MCMR_ADDON_RUNG_v1_2.L5X file

Import Rung					×
Look <u>i</u> n:	🚱 Desktop	-] ← @	- 🖽 🎦	
My Recent Documents Desktop My Documents My Computer	My Computer My Documents My Network Pla Downloads				
	File <u>n</u> ame:	MVI56(E)MCMR_AddOn_Rung_v	v1_4.L5X	•	Import
My Network Places	Files of type:	RSLogix 5000 XML Files (*.L5X)		-	Cancel
Fiddes					Help

This action opens the **IMPORT CONFIGURATION** dialog box, showing the controller tags that will be created.

		Name 🛛 🛆	Alias For	Data Type	Description	Operation
	9	A0I56MCMR 🗸		A0I56MCMR		Create New
	1	CmdControlP1_MSG		MESSAGE		Create New
	Đ	CmdControlP2_MSG		MESSAGE	2	Create New
	ē	CmdControlRespP1_MSG		MESSAGE		Create New
	Đ	CmdControlRespP2_MSG		MESSAGE		Create New
	Ð	CmdErrorP1_MSG		MESSAGE		Create New
	Ð	CmdErrorP2_MSG		MESSAGE		Create New
	Ð	EventCmdP1_MSG		MESSAGE		Create New
	Đ	EventCmdP2_MSG		MESSAGE		Create New
	Đ	EventCmdRespP1_MSG		MESSAGE		Create New
	Đ	EventCmdRespP2_MSG		MESSAGE	0	Create New
	Đ	MCMR		MCMRModule		Create New
	Đ	ModuleStatus_MSG		MESSAGE		Create New
2	Ð	Remote_ENBT:15:I	1	AB:1756_MOD)	Use Existing
2 20	Ð	Remote_ENBT:15:0		AB:1756_MOD)	Use Existing
	Đ	SlaveStatusP1_MSG		MESSAGE		Create New
	Đ	SlaveStatusP2_MSG		MESSAGE		Create New

5 If you are using the module in a different slot (or remote rack), select the correct connection input and output variables that define the path to the module. If your module is located in Slot 1 of the local rack, this step is not required.

		Name d	Alias For	Data Type	Description	10	Dper	ation	
	9	A0I56MCMR		A0I56MCMR			Creat	te New	
	1	CmdControlP1_MSG		MESSAGE		C	Creat	te New	
	1	CmdControlP2_MSG	4	MESSAGE	2	C	Creat	te New	
	Đ	CmdControlRespP1_MS0	à	MESSAGE	1	C	Creat	te New	
	1	CmdControlRespP2_MS	3	MESSAGE		C	Creat	te New	
	1	CmdErrorP1_MSG	1	MESSAGE		C	Creat	te New	
	1	CmdErrorP2_MSG	Ĵ.	MESSAGE		C	Creat	te New	
	19	EventCmdP1_MSG		MESSAGE		C	Creat	te New	
	19	EventCmdP2_MSG		MESSAGE		C	Creat	te New	
	1	EventCmdRespP1_MSG		MESSAGE		Ci		te New	
	Ø	EventCmdRespP2_MSG		MESSAGE		C	Creat	eate New eate New	
	19	MCMR	1	MCMRModule		C	Creat		
-	1	ModuleStatus_MSG		MESSAGE		C	Creat	te New	
2	19	Remote_ENBT:15:1	•	AB:1756_MOD		L	Jse E	Existing	
2	19	Name		Data 1	уре	De		kisting	
	9	Remote_ENBT:1	5:C	AB:17	56_MODULE:C:0		1	New	
	1	Remote_ENBT:1	5:1	AB:17	56_MODULE_INT_84Bytes:	:0	1	New	
		¶	5:0	AB:17	56_MODULE_INT_84Bytes:	0:0			
		¶ ⊕ Remote_ENBT:I		AB:17	56_ENET_17SLOT:I:0				
		-Remote_ENBT:C)	AB:17	56_ENET_17SLOT:0:0		~		
		Controller							
		Program							

6 Click **OK** to confirm the import. RSLogix will indicate that the import is in progress:



When the import is completed, the new rung with the Add-On Instruction will be visible as shown in the following illustration.

RSLogix 5000 - My_Controller [1756-L63]* - [M File Edit View Search Logic Communications Tools		outine*]	
	• <u>minow Liep</u>		
Offline . RUN No Forces . OK	Path: <none></none>		
No Edits		I+ I+ I+ I+ I+ I+ Add-On X Alarms X Bit X Timer/Counter	
Controller Fault Handler			
B B </th <th></th> <th>Add-On - MVI56-MCMR & MVI56E-MCMR modules.</th> <th></th>		Add-On - MVI56-MCMR & MVI56E-MCMR modules.	
Program Program MainRoutine Generation Motion Groups Uncrouped Axes	0 –	Add-On - MVI56-MCMR & MVI56E-MCMR modules. AOI56MCMR & MVI56E-MCMR MOI566MCMR Connection Input Remote ENBT:15:1.Data	-
		Connector Remote_ENBT.15:D.Data MCMR MCMR CmdControlP1 MSG CmdControlP1 MSG	=
Dugic → Prescan → San Types → San Types → San Types		CmdControlP2_MSG CmdControlP2_MSG CmdControlRespP1_MSG CmdControlRespP1_MSG CmdControlRespP2_MSG CmdControlRespP3_MSG CmdControLRespP3_	
M MCMRBlockStats MCMRCmdControl MCMRCMTCNTCOL		CmdErrorP1_MSG CmdErrorP1_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdErrorP2_MSG CmdP1_MSG C	
MCMRDATA		EventCmdP2_MSG EventCmdP2_MSG EventCmdRespP1_MSG EventCmdRespP1_MSG	
開 MCMRPortStats 開 MCMRSTATUS 開 MCMRUTIL 印 G Strings		EventCmdRespP2_MSG EventCmdRespP2_MSG SlaveStatusP1_MSG SlaveStatusP1_MSG SlaveStatusP2_MSG SlaveStatusP2_MSG	
Gradings Gradings	MainRoutine*	ModuleStatus_MSG ModuleStatus_MSG	
Ready	MainProgram	Rung 0 of 1 APP VER	

The procedure has also imported new User Defined Data Types, Controller Tags, and the Add-On instruction for your project.

4	н	Ы		AOI5 GMC	
		avorit	es λ	Add-On	k

7 Save the application and then download the sample ladder logic into the processor.

5.2 Connect your PC to the ControlLogix Processor

There are several ways to establish communication between your PC and the ControlLogix processor. The following steps show how to establish communication through the serial interface. It is not mandatory that you use the processor's serial interface. You may access the processor through whatever network interface is available on your system. Refer to your Rockwell Automation documentation for information on other connection methods.

1 Connect the right-angle connector end of the cable to your controller at the communications port.



2 Connect the straight connector end of the cable to the serial port on your computer.



5.3 Download the Sample Program to the Processor

Note: The key switch on the front of the ControlLogix processor must be in the REM or PROG position.

- 1 If you are not already online with the processor, open the **COMMUNICATIONS** menu, and then choose **DOWNLOAD.** RSLogix will establish communication with the processor. You do not have to download through the processor's serial port, as shown here. You may download through any available network connection.
- 2 When communication is established, RSLogix will open a confirmation dialog box. Click the **DOWNLOAD** button to transfer the sample program to the processor.

Download	
Download to the controller: Name: My_Controller Type: 1756-L63 ControlLogix5563 Contr Path: AB_DF1-1 Security: <none> Download Cancel H</none>	

- **3** RSLogix will compile the program and transfer it to the processor. This process may take a few minutes.
- 4 When the download is complete, RSLogix will open another confirmation dialog box. If the key switch is in the **REM** position, click **OK** to switch the processor from **PROGRAM** mode to **RUN** mode.



Note: If you receive an error message during these steps, refer to your RSLogix documentation to interpret and correct the error.

5.4 Using ProSoft Configuration Builder Software

ProSoft Configuration Builder (PCB) provides a quick and easy way to manage gateway configuration files customized to meet your application needs. *PCB* is not only a powerful solution for new configuration files, but also allows you to import information from previously installed (known working) configurations to new projects.

Note: The MVI56E-MCMR module receives its protocol and backplane configuration information from the *Personality Module* (Compact Flash). Use ProSoft Configuration Builder to configure module settings, and to download changes to the Personality Module.

5.4.1 Upload the Sample Configuration from the Module

The MVI56E-MCMR module contains a sample configuration file, with configuration parameters that match the sample application in this Setup Guide. To retrieve the sample configuration file, follow these steps.

1 In ProSoft Configuration Builder, select the **MVI56E-MCMR** module, and then click the right mouse button to open a shortcut menu. On the shortcut menu, choose **UPLOAD FROM DEVICE TO PC**.



This action opens the **UPLOAD FILES** dialog box.

load files from m	odule to PC			
STEP 1: Select Con	nmunication	Path:		
Select Connectio	n Type:	Etherne	et 💌	Browse Device(s)
Ethernet:	192 .	168 . 0	. 250	Use Default IP
CIPconnect:				CIP Path Edit
STEP 2: Transfer Fi	le(s):			
UPLOAD		Abort		Test Connection
			ОК	Cancel

2 In the UPLOAD FILES dialog box, click BROWSE DEVICES to locate the MVI56E-MCMR module. This action opens the PROSOFT DISCOVERY SERVICE dialog box. Select the module, and then click the right mouse button to open a shortcut menu. On the shortcut menu, choose SELECT FOR PCB. This action places the module's Ethernet address in the Upload Files dialog box.

📓 Prosoft Discov	very Service	
Q		0 -
MVI56 Sn. OL 192.10	Assign Temporary IP Device Details Remove Temporary IP View modules webpage Select for PCB	
Click the search icon I	to begin the browse	

3 Click the **X** in the top right corner to close the ProSoft Discovery Service dialog box.

4 In the **UPLOAD FILES** dialog box, click Upload. When the upload is complete, as shown in the following illustration, click the **OK** button.

Upload files from mo	dule to PC	X
STEP 1: Select Com		
Select Connection		Browse Device(s)
Ethernet:	192 . 168 . 0 . 250	Use Default IP
CIPconnect:		CIP Path Edit
	,	
STEP 2: Transfer File		
UPLOAD	Abort	Test Connection
	01	Cancel

ProSoft Configuration Builder now contains the sample configuration for your MVI56E-MCMR module. In the following steps, you will configure the Read and Write commands.

5.4.2 Enable the Port 1 Master Commands

The default module configuration contains two Modbus Master commands associated to Master Port 1. In the default configuration file, these commands are disabled.

1 To enable the commands, expand the **MVI56E-MCMR** node in ProSoft Configuration Builder until the **MODBUS PORT 1 COMMANDS** tag is visible.

S Untitled - ProSoft Configuration Buil	lder			
<u>File Vi</u> ew <u>P</u> roject <u>T</u> ools <u>H</u> elp				
	Modbus Port 1 Commands All Tags Good			
Ethernet Configuration	[Modbus Port 1 Com START # Enable 1 No 2 No END	mands] Internal Address 1000 0	Poll Interval 0 0	Reg C(10 10
< · · · · · · · · · · · · · · · · · · ·	<			>
Ready		MVI56E-MCMR		

2 Double-click the **MODBUS PORT 1 COMMANDS** tag to open the **EDIT MODBUS PORT 1 COMMANDS** dialog box.

	Enable	Internal Ad	dress Poll Interval	Reg Count	Swap Code	Node Address	ModBus
$\sqrt{1}$	No	1000	0	10	No Change	1	FC 3 - R
√2	No	0	0	10	No Change	1	FC 16 -
<							
	Value Status	s - DK					

3 Select the first command in the list, and then click **EDIT ROW**.

Configure the Modbus Master Read Command

The Modbus Read Command reads 10 words of data from the Quantum processor (Modbus Slave) and transfers it to the MVI56E-MCMR module's internal database. The following table describes the relationship between memory addresses in the Modbus Master (MVI56E-MCMR) and the Modbus Slave (Quantum processor).

1000 400801 1001 400802 1002 400803 1003 400804 1004 400805 1005 400806 1006 400807 1007 400808	ess
1002 400803 1003 400804 1004 400805 1005 400806 1006 400807	
1003 400804 1004 400805 1005 400806 1006 400807	
1004 400805 1005 400806 1006 400807	
1005 400806 1006 400807	
1006 400807	
1007 100808	
400808	
1008 400809	
1009 400810	

In the sample configuration, the Modbus Read Command is present, but disabled. To enable the command, change the **ENABLE** field from No to **YES**, as shown in the following illustration.

E	dit - Row 1			×
	Enable Internal Address	Yes 1000	Enable	
	Poll Interval Reg Count Swap Code Node Address ModBus Function MB Address in Device Comment	0 10 No Change 1 FC 3 - Read Holding Registers 800 read from 400801 to db addre	Yes	•
			This field defines whether or not the command is to be executed and under what conditions.	~
			Disable (0) = The command is disabled and will not be executed in the normal polling sequence.	
			Enable (1) = The command is executed each scan of the command list if the Poll Interval Time is set to zero. If the Poll Interval time is set, the	~
			Reset Tag Reset All	
			OK Cancel	

Notes:

- Func 3 represents Modbus Function Code 3, the command code to Read Holding Registers
- The DevAddress parameter is 0-based so 800 = 400801, 801 = 400802, and so on.
- The Enable code must be set to 1 to enable the command (0 = disable)
- The destination Slave node address must be set as 1 (Node parameter)

Configure the Modbus Master Write Command

The Modbus Write Command will write data from the MVI56E-MCMR module to the Quantum processor as follows.

MVI56E-MCMR Database Address	Quantum Memory Address
0	400401
1	400402
2	400403
3	400404
4	400405
5	400406
6	400407
7	400408
8	400409
9	400411

In the sample configuration, a Modbus Write Command is present, but disabled. To enable this command, change the **ENABLE** field from No to **YES**, as shown in the following illustration.

Enable	Yes	Enable	
Internal Address Poll Interval Reg Count Swap Code Node Address ModBus Function MB Address in Device Comment	0 0 10 No Change 1 FC 16 - Preset (Write) Multiple 400 write from db address 0 to 40(Yes Definition:	
		This field defines not the command executed and unc conditions. Disable (0) = The disabled and will executed in the n sequence. Enable (1) = The executed each so command list if th Time is set to zer Interval time is so	is to be ler what command is not be ormal polling command is an of the Poll Interval o. If the Poll
		Reset Tag	Reset <u>A</u> ll

Notes:

- Func 16 represents Modbus Function Code 16, the command code to Preset (Write) Holding Registers
- The DEVADDRESS parameter is 0-based so 400 = 400401, 401 = 400402, and so on.
- The ENABLE code must be set to 1 to enable the command (0 = disable).
- The destination Slave node address must be set as 1 (Node parameter)

5.5 Download the Project to the Module

In order for the module to use the settings you configured, you must download (copy) the updated Project file from your PC to the module.

- 1 In the tree view in ProSoft Configuration Builder, click once to select the MVI56E-MCMR module.
- 2 Open the **PROJECT** menu, and then choose **MODULE / DOWNLOAD.**

This action opens the **DOWNLOAD** dialog box. Notice that the Ethernet address field contains the temporary IP address you assigned in the previous step. ProSoft Configuration Builder will use this temporary IP address to connect to the module.

Download files from PC to module				
STEP 1: Select Comm	nunication Path:			
Select Connection	Type: Ethernet 💌	Browse Device(s)		
Ethernet:	192 . 168 . 0 . 250	Use Default IP		
CIPconnect:		CIP Path Edit		
STEP 2: Transfer File(s):			
DOWNLOAD	Abort	Test Connection		
		DK Cancel		

Click **TEST CONNECTION** to verify that the temporary IP address is correct.

3 If the connection succeeds, click **DOWNLOAD** to transfer the Ethernet configuration to the module.

If the Test Connection procedure fails, you will see an error message. To correct the error, follow these steps.

- 1 Click **OK** to dismiss the error message.
- 2 On the **DOWNLOAD** dialog box, click **BROWSE DEVICES** to open **PROSOFT DISCOVERY SERVICE**.

Prosoft Disco	very Service	
A Proson Disco	Assign Temporary IP	• • •
Click the search icon	to begin the browse	

- **3** Select the module, and then click the right mouse button to open a shortcut menu. On the shortcut menu, choose **SELECT FOR PCB**.
- 4 Close ProSoft Discovery Service.
- **5** Click **DOWNLOAD** to transfer the configuration to the module.

5.6 Configure the Quantum Processor as a Modbus Slave

The next part of this tutorial is to configure the remote Modbus Slave. For this example, the Modbus Slave will be a Quantum processor.

The communication port settings for the Modbus Slave must match the Port 1 settings for the Modbus Master. Use the values in the following table to configure the Quantum processor with Schneider Electric's Concept programming software (version 2.6 or higher).

Parameter	Value
Node Address	1
Modbus Protocol	RTU
Baud Rate	19200
Parity	None
Data Bits	8
Stop Bits	1

The following illustration shows the **MODBUS PORT SETTINGS** dialog box in Concept version 2.6.

Мо	dbus Port Se	ttings - R	ead Only						×
								Eridge N	/lode
	Baud	Data bits	Stop bits	Parity	Delay (ms)	Address	Head slot	Mode	Protocc
1	19200	8	1	None	10	1	0	RTU	RS232
			-					-	
Ľ		0K.		Car	ncel		Help		

5.7 Connect the MVI56E-MCMR Module to the Quantum Processor

The final part of this tutorial is to connect the supplied RJ45 to DB9 adaptor and the supplied null modem cable to Port 1 on the MVI56E-MCMR module, and Modbus Comm1 on the Quantum processor.

The following illustration shows the serial connection between the MVI56E-MCMR module and the Quantum processor.



5.8 Verify Communication

There are several ways to verify that the MVI56E-MCMR module is communicating with the processor and with the Modbus Master/Slave network. You can:

- View Exchanged Data
- View the Module Status in the RSLogix 5000 Controller Tags
- View the LED Status Indicators

5.8.1 View Exchanged Data

The following illustration describes the source and destination for the data exchanged by the two Modbus Master Commands.



Check Write Data

The following steps show you how to verify that the WriteData Command is working.

- 1 In RSLogix, navigate to the processor controller tags MCMR.DATA.WRITEDATA[0] through MCMR.DATA.WRITEDATA[9].
- 2 For words [0] through [9], enter the numbers shown in the following illustration.

-MCMR.DATA.WriteData	{}
-MCMR.DATA.WriteData[0]	1
HCMR.DATA.WriteData[1]	2
	3
	4
	5
-MCMR.DATA.WriteData[5]	6
	7
	8
	9
+-MCMR.DATA.WriteData[9]	10
	0

This action sends the values you entered to the Modbus Master Port on the MVI56E-MCMR, and then to the Quantum processor, where you will be able to see the data in Concept.

3 In Concept, navigate to the **REFERENCE DATA EDITOR** to monitor the processor memory addresses from 400401 through 400410. The data should match the data you sent from RSLogix 5000.

R	📓 RDE Template (untitled) - Animation ON				
	Variable Name	Data Type	Address	Value	
1					
2			400401	1	
3			400402	2	
4			400403	3	
5			400404	4	
6			400405	5	
7			400406	6	
8			400407	7	
9			400408	8	
10			400409	9	
11			400410	10	

Check Read Data

The following steps show you how to verify that the ReadData Command is working.

1 In Concept, navigate to the **REFERENCE DATA EDITOR**, and enter the following values in processor memory addresses from 400801 through 400810 as shown in the following illustration.

<u>e</u> f	📓 RDE Template (untitled) - Animation ON				
	Variable Name	Data Type	Address	Value	
14					
15			400801	101	
16			400802	102	
17			400803	103	
18			400804	104	
19			400805	105	
20			400806	106	
21			400807	107	
22			400808	108	
23			400809	109	
24			400810	110	

This action populates the memory addresses in the Quantum processor that the MVI56E-MCMR will attempt to retrieve with the ReadData Command.

2 In RSLogix 5000, the values in **MCMR.DATA.READDATA[0]** through **[9]** should match the data you entered in Concept.

-MCMR.DATA.ReadData	{}
E→MCMR.DATA.ReadData[0]	101
HCMR.DATA.ReadData[1]	102
⊞-MCMR.DATA.ReadData[2]	103
⊕-MCMR.DATA.ReadData[3]	104
MCMR.DATA.ReadData[4]	105
⊕-MCMR.DATA.ReadData[5]	106
⊕-MCMR.DATA.ReadData[6]	107
⊕-MCMR.DATA.ReadData[7]	108
⊕-MCMR.DATA.ReadData[8]	109
⊕-MCMR.DATA.ReadData[9]	110

Tip: Repeat these tests, using different values each time, to verify that the same data appears in the proper place in each processor.

5.8.2 Check Module Status through ControlLogix Controller Tags

You can view network status through the ControlLogix controller tags that are updated through the MVI56E-MCMR sample ladder.

To verify that the Modbus Master is communicating with one or more Modbus Slaves, view the contents of the two ReadData array elements beginning at the address you used for the **COMMAND ERROR POINTER** parameter, minus the value of the **READ REGISTER START** parameter.

Edit - Modbus Port 1		
Enabled Type Protocol Baud Rate Parity Data Bits Stop Bits RTS On RTS Off Use CTS Line Float Flag Float Start Float Offset Internal Slave ID Minimum Response Delay Bit Input Offset Word Input Offset Output Offset Use Guard Band Timeout Function 99 Offset Mard Band Timeout Function 99 Offset Minimum Command Delay Command Error Pointer	Yes Master RTU 19200 None 8 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Command Error Pointer 1500 Comment: Definition: Internal database location of command error list. 1 word for each command.]
Response Timeout Retry Count	3	Reset Tag Reset All OK Cancel

In this case, the **COMMAND ERROR POINTER** was set to 1500 and the **READ REGISTER START** to 1000. This means that (1500 - 1000 = 500); so **READDATA[500]** and **READDATA[501]** will tell you the individual status of each of the two commands issued by the module.

To verify that the Modbus Slave is communicating with a Modbus Master, view the contents of the **MCMR.STATUS.Port1Stats** tag for total commands issued, responses received, errors, and so on. Set the

MCMR.STATUS.PORTXSTATS.PORTTRIGGER register to 1 to refresh the status data.

-MCMR.STATUS.Port1Stats	{}
-MCMR.STATUS.Port1Stats.PortTrigger	0
How MCMR.STATUS.Port1Stats.CmdReq	569
HCMR.STATUS.Port1Stats.CmdResp	568
MCMR.STATUS.Port1Stats.CmdEn	0
-MCMR.STATUS.Port1Stats.Requests	569
-MCMR.STATUS.Port1Stats.Responses	569
⊕-MCMR.STATUS.Port1Stats.ErrSent	0
⊕-MCMR.STATUS.Port1Stats.ErrRec	0

The following controller tags should continuously increment at every **PORTTRIGGER** set, indicating that Port 1 is continuously sending commands and receiving responses:

- MCMR.STATUS.Port1Stats.CmdReq
- MCMR.STATUS.Port1Stats.CmdResp
- MCMR.STATUS.Port1Stats.Requests
- MCMR.STATUS.Port1Stats.Responses

If the error counters continuously increment, the **LASTERROR** controller tag value shows the command index that caused the latest failure.

1
0
0
0

5.8.3 Scrolling LED Status Indicators

The scrolling LED display indicates the module's operating status as follows:

Code	Message	
Boot / DDOK	Module is initializing	
Ladd	Module is waiting for required module configuration data from ladder logic to configure the Modbus ports	
Waiting for Processor Connection	 Module did not connect to processor during initialization Sample ladder logic or AOI is not loaded on processor Module is located in a different slot than the one configured in the ladder logic/AOI Processor is not in RUN or REM RUN mode 	
Last config: <date></date>	Indicates the last date when the module changed its IP address. You can update the module date and time through the module's web page, or with the MVI56E Optional Add-On Instruction.	
Config P1/P2 <modbus mode=""> <port type=""> <baud> <parity> <data bits=""> <stop bits=""> <rs Interface> <id (slave)=""> <cmds: (Master)></cmds: </id></rs </stop></data></parity></baud></port></modbus>	 After power up and every reconfiguration, the module will display the configuration of both ports. The information consists of: Modbus mode: RTU/ASCII Port type: Master/Slave Baud: 115200 / 57600 / 38400 / 19200 / 9600/ 4800 / 2400 / 1200 / 600 / 300 Parity: None / Even / Odd Data bits: 7 / 8 Stop bits: 1 / 2 RS Interface: RS-232 / RS-422 / RS-485 ID: Slave Modbus Address Cmds: Configured Modbus Master Commands 	

Initialization Messages

Operation Messages

After the initialization step, the following message pattern will be repeated.

<Backplane Status> <IP Address> <Backplane Status> <Port Status>

Code	Message
<backplane status=""></backplane>	OK: Module is communicating with processor ERR: Module is unable to communicate with processor. For this scenario, the <port status=""> message above is replaced with "Processor faulted or is in program mode".</port>
<ip address=""></ip>	Module IP address
<port status=""></port>	OK: Port is communicating without error Master/Slave Communication Errors: port is having communication errors. Refer to PCB diagnostics for further information about the error.

5.8.4 Ethernet LED Indicators

LED	State	Description
Data	Off	Ethernet connected at 10Mbps duplex speed
	Amber Solid	Ethernet connected at 100Mbps duplex speed
Link	Off	No physical network connection is detected. No Ethernet communication is possible. Check wiring and cables.
	Green Solid or Blinking	Physical network connection detected. This LED must be on solid for Ethernet communication to be possible.

The Ethernet LEDs indicate the module's Ethernet port status as follows:

5.8.5 Non-Scrolling LED Status Indicators

The non-scrolling LEDs indicate the module's operating status as follows:

LED Label	Color	Status	Indication
APP	Red or Green	OFF	The module is not receiving adequate power or is not securely plugged into the rack. May also be OFF during configuration download.
		GREEN	The MVI56E-MCMR is working normally.
		RED	 The most common cause is that the module has detected a communication error during operation of an application port. The following conditions may also cause a RED LED: The firmware is initializing during startup The firmware detects an on-board hardware problem during startup Failure of application port hardware during startup The module is shutting down The module is rebooting due to a ColdBoot or WarmBoot request from the ladder logic or Debug Menu
ОК	Red or Green	OFF	The module is not receiving adequate power or is not securely plugged into the rack.
		GREEN	The module is operating normally.
		RED	The module has detected an internal error or is being initialized. If the LED remains RED for over 10 seconds, the module is not working. Remove it from the rack and re-insert it to restart its internal program.
ERR	Red	OFF	The battery voltage is OK and functioning.
		ON	The battery voltage is low or battery is not present. Allow battery to charge by keeping module plugged into rack for 24 hours. If ERR LED still does not go off, contact ProSoft Technology, as the battery is not a user-serviceable item.

6 Building on Success

In This Chapter

Now that you have successfully installed, configured, and verified operation of the MVI56E-MCMR module, you should have a better understanding of how to make it work for your specific application. The following resources are available to help you build on your success.

- For more information about the MVI56E-MCMR module, including detailed hardware and software configuration, troubleshooting, and application information, refer to the MVI56E-MCMR User Manual.
- For technical support and warranty information for your MVI56E-MCMR module, refer to Support, Service, and Warranty in the MVI56E-MCMR User Manual.
- For more information on ProSoft Technology products and services, please visit www.prosoft-technology.com.

6.1 Frequently Asked Questions

6.1.1 What are the differences between the MVI56 and the MVI56E modules? What does the "E" stand for?

The "E" stands for *E*nhanced with *E*thernet communication capabilities. The new enhancements are:

- PCB: MVI56E-MCMR products now use PCB (ProSoft Configuration Builder) software, a Windows-based configuration utility providing a new graphic user interface for module diagnostics with screen navigation improving interoperability with the module.
- Seamless Migration: MVI56E products are backward compatible with existing ladder logic and module configuration files allowing for a smooth "plug and play" transition when replacing the earlier version MVI56-MCMR product.
- Personality Memory Module: The module incorporates a non-volatile CF memory card for storing the module's configuration data (or personality). This feature benefits the end-user with quick replacement of faulted modules and restoration of systems by a simple exchange of the Personality Memory Module with absolutely no PC or configuration requirements.
- Ethernet Configuration Port: Allows for remote module connectivity. Replaces serial communication port becoming the primary configuration port with a web server interface.
- Web server: Provides HTML information about the status of the product and download access to documents and software such as the product manual and configuration software. Components are stored locally in the module's flash memory.
- LED Display: The LED provides additional detailed plain English diagnostic and error information for the module, backplane communication, and network conditions.
- Discovery Service: Allows PCB configuration software (or separate utility) to find and display products located on the network with key product attributes such as name, serial number, and IP address. The user will be able to change IP address, upload/download, and enter into diagnostics from the list.
- CIPconnect[®] enabled: Allows end-users to connect from remote locations to local and remote chassis installed MVI56E modules from anywhere.

6.1.2 Is the MVI56E product a direct replacement to my existing MVI56 product?

Yes

6.1.3 How is the MVI56E-MCMR configured?

The module is configured with ProSoft Configuration Builder, which creates the necessary configuration files to download to the MVI56E-MCMR module.

6.1.4 What is ProSoft Configuration Builder (PCB)?

ProSoft Configuration Builder (PCB) provides a quick and easy way to manage module diagnostics and troubleshooting operations. Built-in module diagnostics menus and the serial port data stream analyzer can be accessed using PCB through the module's high-speed Ethernet configuration port (E1) or though Rockwell Automation 1756-ENxT or 1756-CNBx communications interfaces using CIPconnect[®].

6.1.5 What is the purpose of the MVI56E-MCMR Ethernet (E1) Port?

The MVI56E-MCMR Ethernet Port (E1) allows a remote PC to configure and monitor the module operation through ProSoft Configuration Builder (PCB).

The Ethernet Port (E1) is also used to set the module's IP address. You can also set the IP address with ladder logic. Refer to the MVI56E-MCMR User Manual for more information on these tasks.

6.1.6 How do I change the module's IP address?

- 1 Use ProSoft Configuration Builder to edit and download the Ethernet configuration to the module.
- 2 Use the Optional Add-On Instruction (AOI) provided with the module. The AOI can be downloaded from the module's web page.

6.1.7 Does the MVI56E-MCMR module require processor logic?

Yes, ladder logic is required for data transfer between the MVI56E module and the ControlLogix[®] processor.

- For RSLogix[™] 5000 version 16 applications (or later), the included Add-On Instruction encapsulates the entire ladder logic into one single instruction.
- For RSLogix 5000 version 15 and older, sample ladder logic is available from the ProSoft Technology[®] website at www.prosoft-technology.com.

6.1.8 What is the purpose of the Optional MVI56E-MCMR Add-On Instruction?

The Optional Add-On Instruction (AOI) allows the processor to perform the following tasks:

- 1 Set the MVI56E Ethernet settings
- 2 Read the MVI56E Ethernet settings
- 3 Set MVI56E date/time information
- 4 Read the MVI56E date/time information

Items 1 and 2 can also be performed through ProSoft Configuration Builder (PCB) using ProSoft Discovery Service. Items 3 and 4 can also be performed through the module's built-in web page.

The Optional AOI is needed only for specific applications where Ethernet or CIPconnect access from a programmer's personal computer (PC) to the module is not possible.

6.1.9 What is ProSoft Discovery Service (PDS)?

ProSoft Discovery Service (PDS) is Windows-based software that connects to the Ethernet port of the module for the following purposes:

- Automatic module discovery on the Ethernet network
- Set a temporary IP address for the module for easy commissioning
- Allow PCB to select the module for monitoring and IP address reconfiguration

The ProSoft Discovery Service software is supplied as a stand-alone utility, as well as being integrated into PCB.

6.1.10 How do I monitor MVI56E-MCMR operation?

Module operation can be monitored either through the processor controller tags or through the ProSoft Configuration Builder diagnostic window. Available status information includes number of messages sent, number of messages received, number of errors, and error codes.

6.1.11 Are there any other ways to monitor module diagnostics besides being connected to the module's network (subnet)?

PCB can monitor the module via ControlLogix backplanes and process networks using CIPconnect. The PC running PCB can use its Ethernet port to connect to any 1756-ENxT EtherNet/IP[™] interface module which is on the same Ethernet subnet. Through this connection, PCB can use CIPconnect to route through the ControlLogix backplane to other 1756-ENxT or 1756-CNBx modules, for up to five more route links, to reach an MVI56E module in a chassis connected on EtherNet/IP or ControlNet[™] process networks.

7 Glossary of Terms

Α

ASCII

American Standard Code for Information Interchange. A communication mode in which each eight-bit byte in a message contains one ASCII character code. ASCII characters (or hexadecimal characters) are sometimes used as a key to encrypt data and ensure its secure transmission.

В

Baud Rate

The speed of communication between devices on the network. All devices must communicate at the same rate.

С

Client

A client is a software program, or the device on which that program runs, that makes requests for information from a software program, or the device on which that program runs, in a client-server relationship.

A Client on an Ethernet network is equivalent to a Master on a serial network.

D

Default Gateway

The IP address of a network router where data is sent if the destination IP address is outside the local subnet. The gateway is the device that routes the traffic from the local area network to other networks such as the Internet.

Е

ESD

Electrostatic Discharge. Can cause internal circuit damage to the coprocessor.

Ethernet

A set of network cabling and network access (CSMA/CD) protocol standards for bus topology computer networks invented by Xerox but now controlled by the 802.3 subcommittee of the IEEE. F

Firmware

Software for embedded computers.

Full-Duplex

A communications circuit or system designed to simultaneously transmit and receive two different streams of data. Telephones are an example of a full-duplex communication system. Both parties on a telephone conversation can talk and listen at the same time. If both talk at the same time, their two signals are not corrupted.

Η

Half-Duplex

A communications circuit or system designed to transmit and receive data, but not both simultaneously. CB or walkie-talkie radios are an example of a halfduplex communication system. Either parties on a radio conversation may talk or listen; but both cannot talk at the same time without corrupting each other's signal. If one operator is "talking", the other must be "listening" to have successful communication.

IP Address

A 32-bit identification number for each node on an Internet Protocol network. These addresses are represented as four sets of 8-bit numbers (numbers from 0 to 255), separated by periods ("dots").

L

Networks using the TCP/IP Protocol route messages based on the IP address of the destination. Each number can be 0 to 255. For example, 192.168.0.100 could be an IP address. Each node on the network must have a unique IP address.

L

LED

Light-emitting diode.

Μ

MAC ID

A hexadecimal number that uniquely identifies an Ethernet device.

Master

A Master is a device that makes requests for information from a software program, or the device on which that program runs, in a Master-Slave relationship.

A Client on an Ethernet network is equivalent to a Master on a Serial network.

Ν

Network

A series of stations or nodes connected by some type of communication medium. A network may consist of a single link or multiple links.

Node

An address or software location on the network.

Ρ

Peer-to-Peer

A network relationship between devices where each device can send commands as a master or client, and respond to commands as a slave or server.

Power Supply

Device that supplies electrical power to the I/O chassis containing the processor, coprocessor, or other modules.

Protocol

The language or packaging of information that is transmitted between nodes on a network.

R

RS-232

Recommended Standard 232; the standard for serial binary signals between DTE and DCE devices.

S

Serial Data/Serial Data Transmission

Data that is transferred one bit at a time. Serial data transmission involves changing a carrier signal line between two possible states to indicate a binary 0 or binary 1 value. Successive data bits are rapidly transmitted one after the other with a fixed time allowed for each bit. Data bits are usually grouped into "packets", which contain a specific amount of data bits, along with extra bits included to provide error-checking capability.

Server

A Server is a software program, or the device on which that program runs, that provides a specific kind of service to a Client software program, or the device on which that program runs, on an Ethernet network.

A Server on an Ethernet network is equivalent to a Slave on a Serial network.

Simplex

A communications circuit or system designed to either transmit data or receive data, but not both. Broadcast television is an example of simplex communication system. A television station sends a TV signal but cannot receive responses back from the television sets to which it is transmitting. The TV sets can receive the signal from the TV station but cannot transmit back to the station.

Slave

A Slave is a software program, or the device on which that program runs, which provides a specific kind of service to a Master software program, or the device on which that program runs, on a serial network.

A Slave on a Serial network is equivalent to a Server on an Ethernet network.

Subnet Mask

A mask used to determine what subnet an IP address belongs to. An IP address has two components: the network address, and the host (node or device) address. For example, consider the IP address 150.215.017.009. Assuming this is part of a Class B network (with a subnet mask of 255.255.0.0), the first two numbers (150.215) represent the Class B network address, and the second two numbers (017.009) identify a particular host on this network.

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